

Coupled metapopulation dynamics with patch modification and memory

Zachary R. Miller and Stefano Allesina

University of Chicago

zachmiller@uchicago.edu

ESA | August 2021

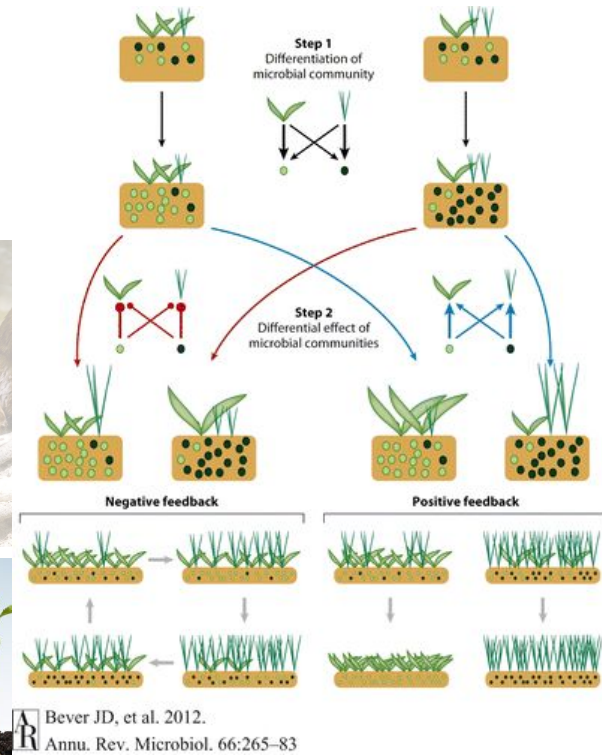
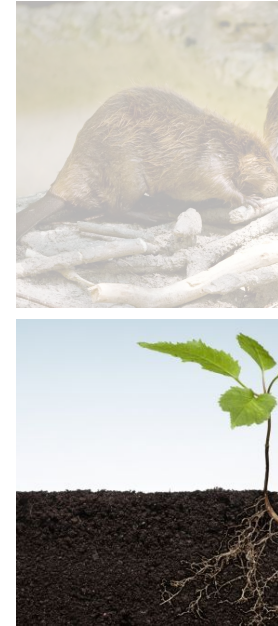
Ecosystem engineering everywhere

- All organisms modify their environment, and react to environmental state
- Environmental modification mediates interactions in many communities
- Classical ecological theory studies some special cases (e.g. resource competition), usually *locally*
- **What do community dynamics look like on the landscape scale?**



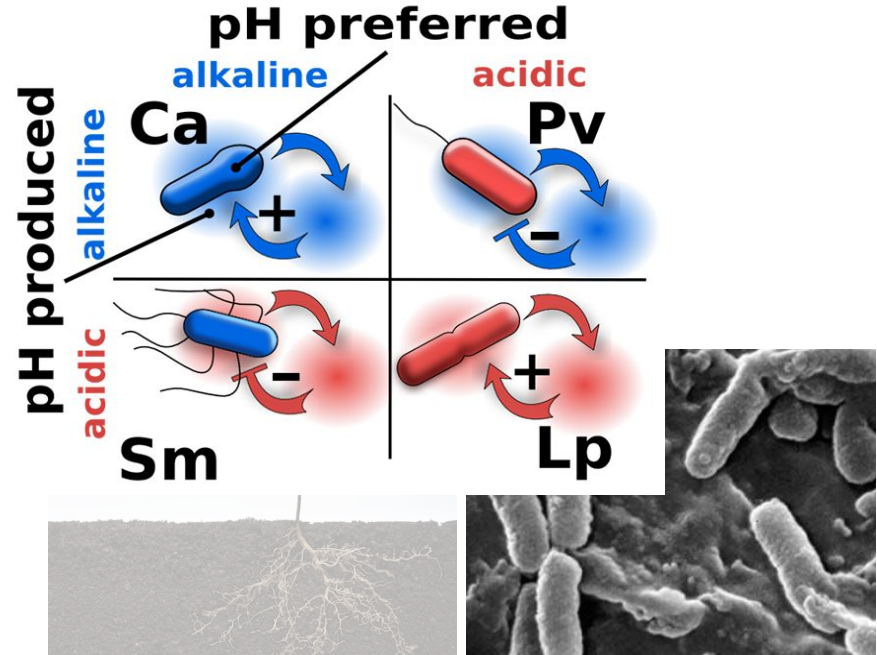
Ecosystem engineering everywhere

- All organisms modify their environment, and react to environmental state
- Environmental modification mediates interactions in many communities
- Classical ecological theory studies some special cases (e.g. resource competition), usually *locally*
- What do community dynamics look like on the landscape scale?



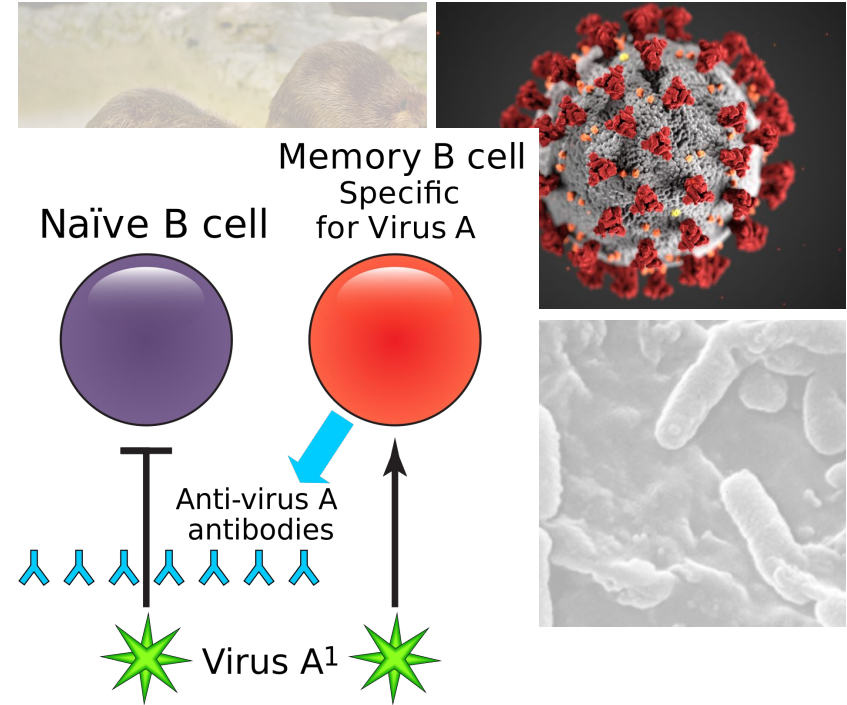
Ecosystem engineering everywhere

- All organisms modify their environment, and react to environmental state
- Environmental modification mediates interactions in many communities
- Classical ecological theory studies some special cases (e.g. resource competition), usually *locally*
- What do community dynamics look like on the landscape scale?



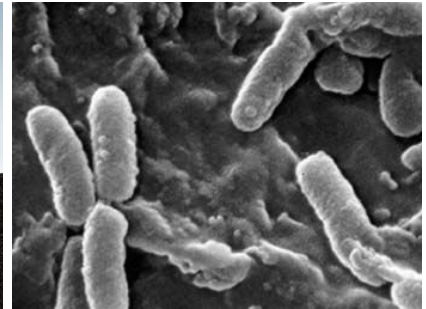
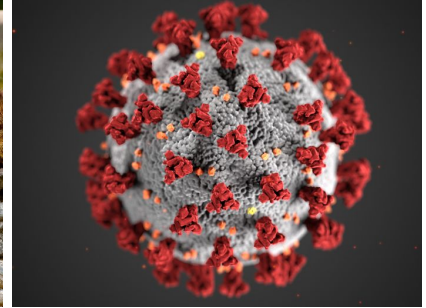
Ecosystem engineering everywhere

- All organisms modify their environment, and react to environmental state
- Environmental modification mediates interactions in many communities
- Classical ecological theory studies some special cases (e.g. resource competition), usually *locally*
- **What do community dynamics look like on the landscape scale?**



Ecosystem engineering everywhere

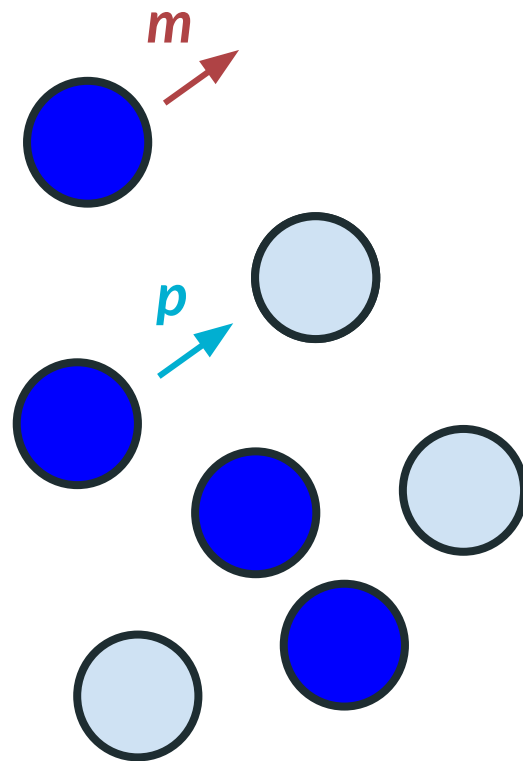
- All organisms modify their environment, and react to environmental state
- Environmental modification mediates interactions in many communities
- Classical ecological theory studies some special cases (e.g. resource competition), usually *locally*
- **What do community dynamics look like on the landscape scale?**



Metapopulation models

Levins (1969) introduced a simple model for **migration** and **extinction** in a landscape:

$$\frac{dx}{dt} = -\underset{\substack{\uparrow \\ \text{Extinction} \\ \text{rate}}}{m} x + \underset{\substack{\uparrow \\ \text{Fraction} \\ \text{occupied}}}{p} x \underbrace{(1 - x)}_{\substack{\text{Colonization} \\ \text{rate}} \quad \text{Fraction unoccupied}}$$



Metapopulation models

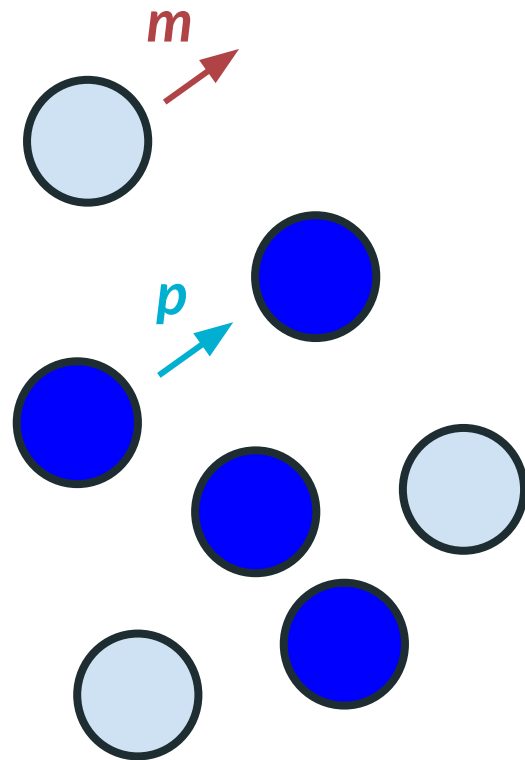
Levins (1969) introduced a simple model for migration and extinction in a landscape:

$$\frac{dx}{dt} = -m x + p x (1 - x)$$

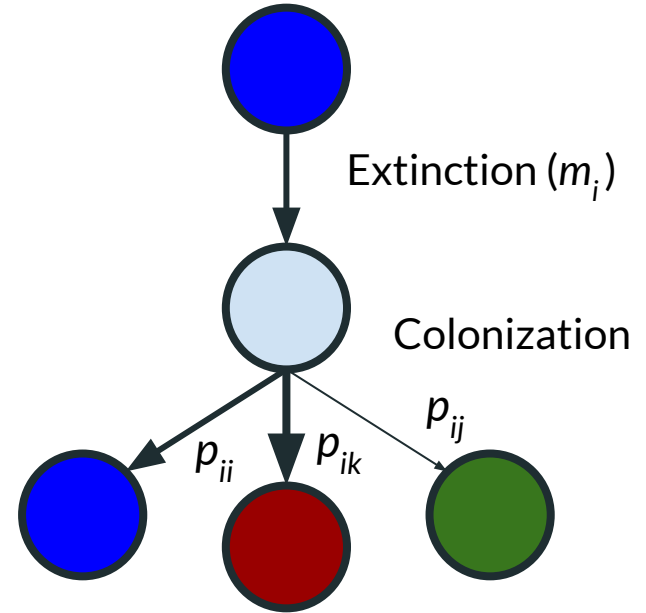
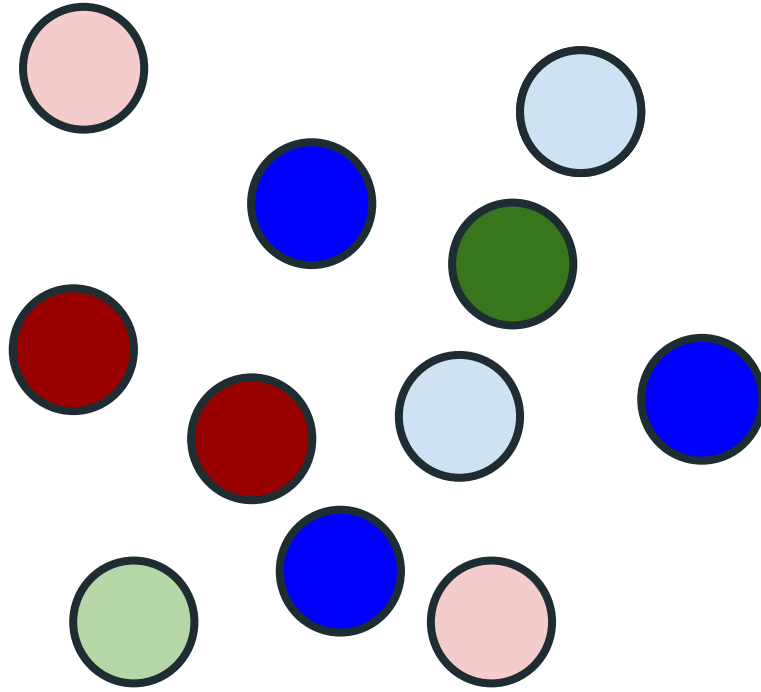
An equivalent (SIS-like) description:

$$\frac{dx}{dt} = -m x + p x y$$

$$\frac{dy}{dt} = m x - p x y$$

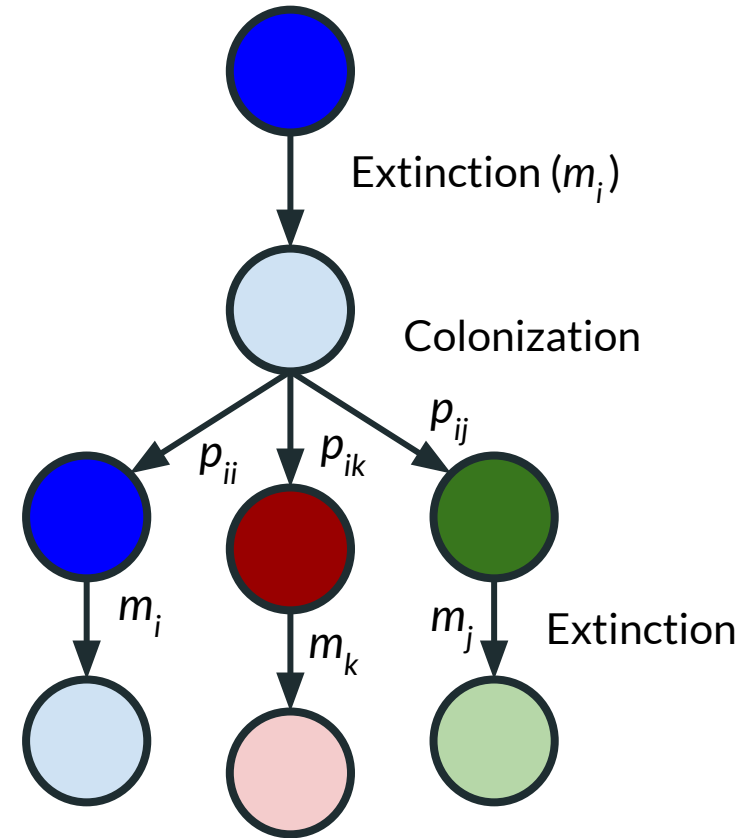


Patch modification and memory



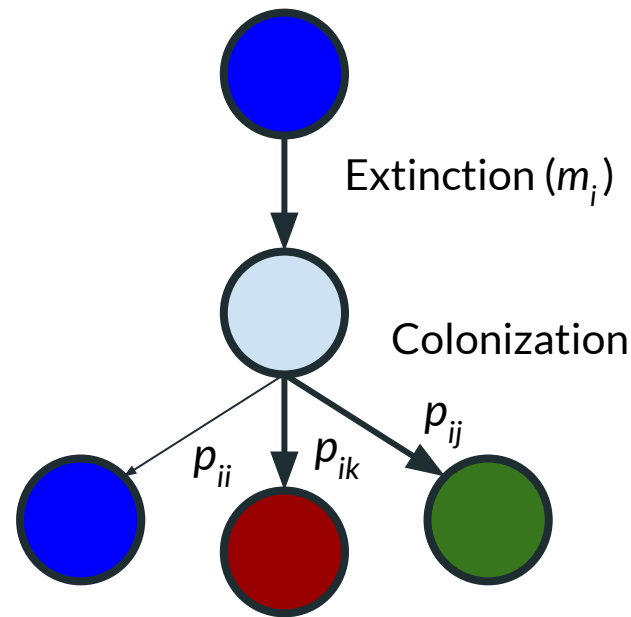
Patch modification and memory

- Patch modification is incorporated implicitly, through state-specific colonization probabilities (p_{ij})
- Patch state depends on the last occupant only
- Patch “memory” is permanent until re-set by new colonizer
- Extinction/mortality rates (m_i) are species-specific, and insensitive to patch state



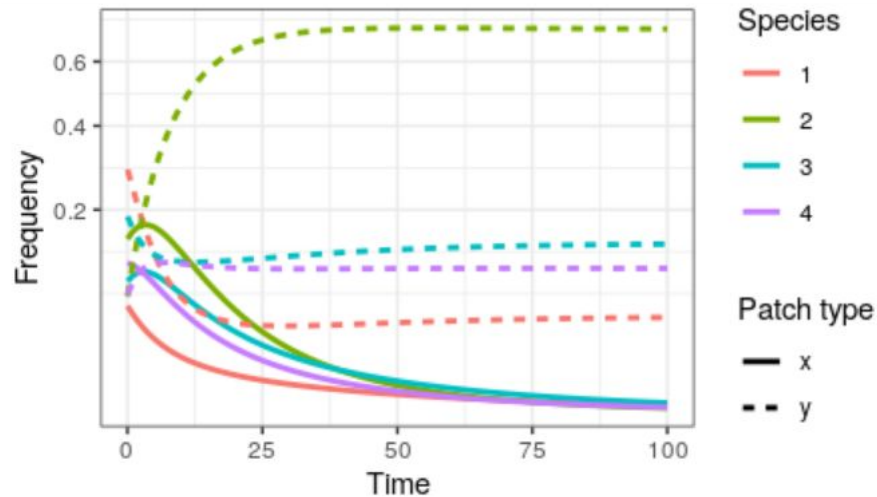
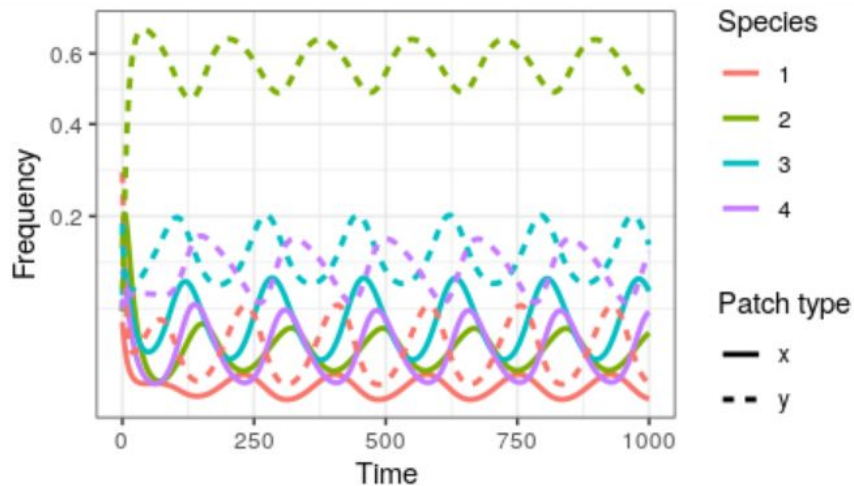
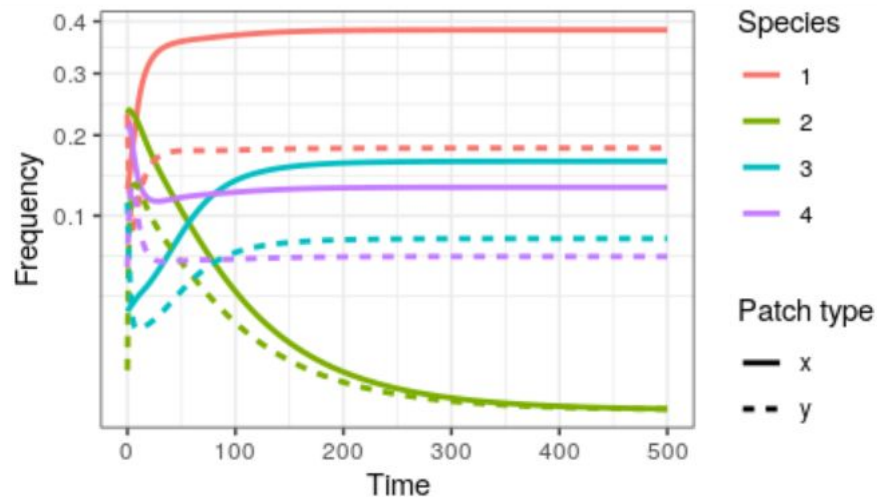
Patch modification and memory

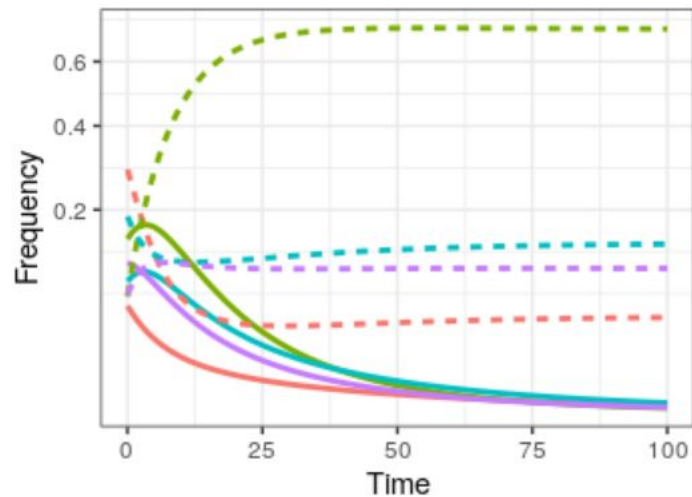
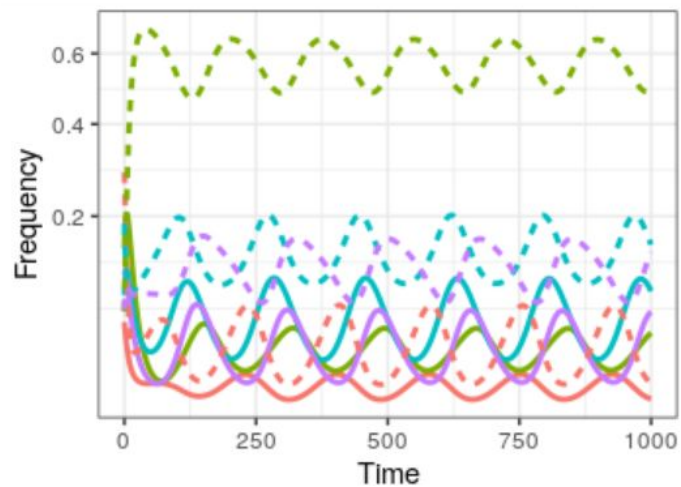
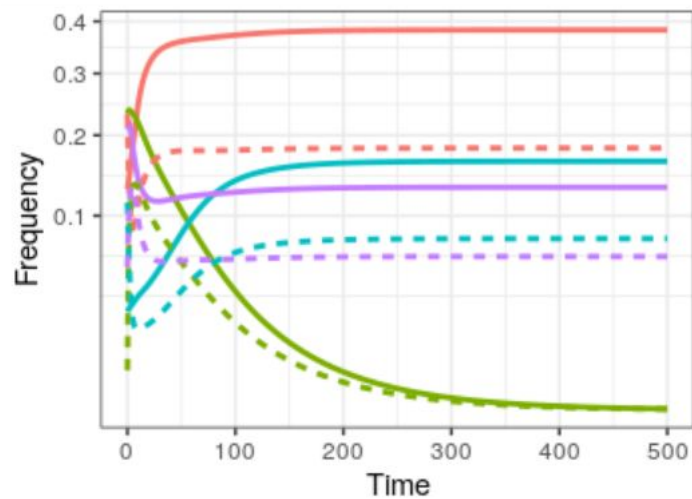
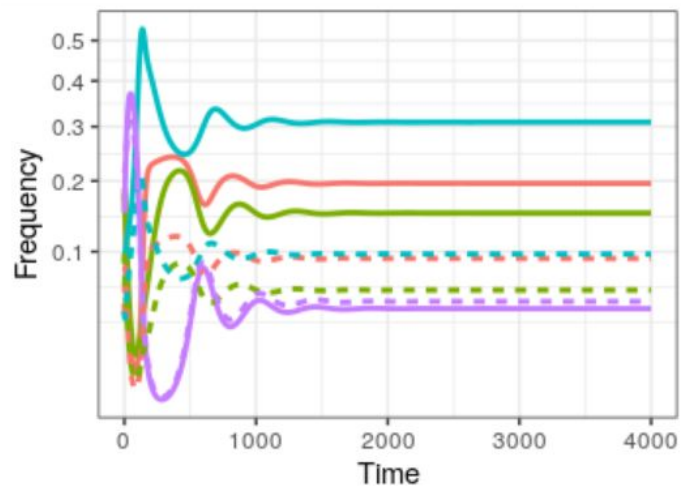
$$\begin{aligned}\frac{dx_i}{dt} &= \overset{\text{Local extinction}}{-m_i x_i} + \overset{\text{Colonization}}{x_i \sum_j p_{ij} y_j} \\ \frac{dy_i}{dt} &= m_i x_i - y_i \sum_j p_{ji} x_j\end{aligned}$$



$$\frac{dx_i}{dt} = -m_i x_i + x_i \sum_j p_{ij} y_j$$

$$\frac{dy_i}{dt} = m_i x_i - y_i \sum_j p_{ji} x_j$$





Long-term dynamics

Existing literature focuses on **positive** vs. **negative** feedbacks:

Patches last occupied by a conspecific might have:

- Suitable abiotic conditions (e.g. pH, fire)
- Symbionts / mutualists present
- Immunodeficiency or antibody-dependent enhancement

...but also

- Depleted or degraded resources / environment
- Specific predators / parasites/ pathogens present
- Specific immunity

Positive feedbacks should be **destabilizing**, while **negative feedbacks** should be **stabilizing** (enhance coexistence)

Long-term dynamics: The simplest case

A minimal model where $m_i = m$, and p_{ij} depends only on $i = j$ or $i \neq j$

$$P = \alpha I + \beta \mathbf{1}\mathbf{1}^T = \begin{pmatrix} \alpha + \beta & \beta & \beta & \dots \\ \beta & \alpha + \beta & \beta & \dots \\ \beta & \beta & \alpha + \beta & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

$$y^* = \frac{m}{\alpha + \beta n}$$

$$x^* = \frac{1}{n} - y^*$$

Feasibility requires:

$$m < \beta + \frac{\alpha}{n}$$

Long-term dynamics: The simplest case

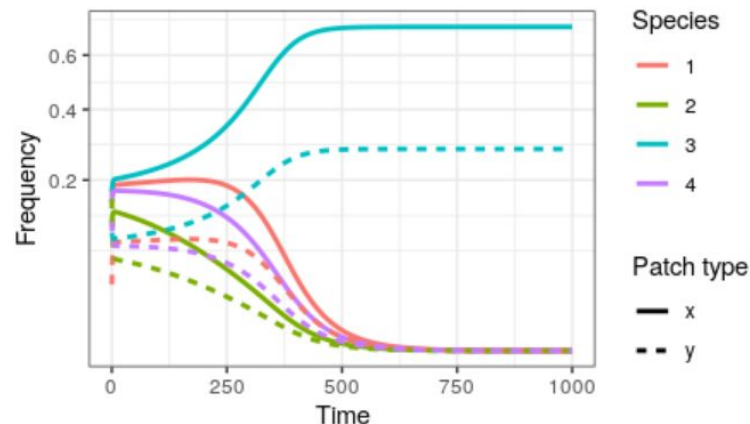
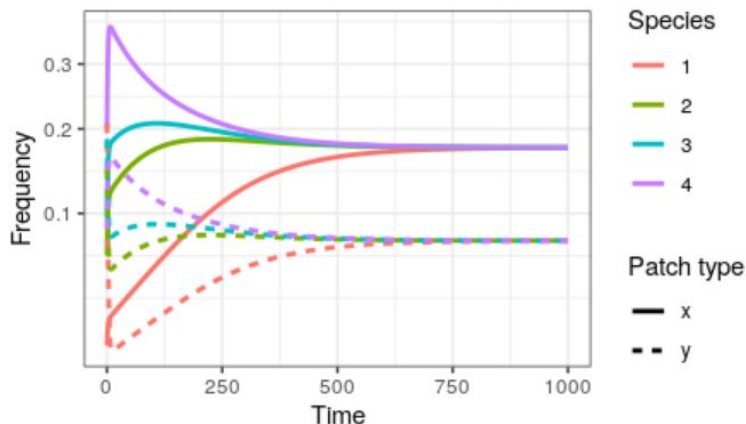
$$P = \alpha I + \beta 11^T$$

- When will the system approach the n -species equilibrium?

Long-term dynamics: The simplest case

$$P = \alpha I + \beta 11^T$$

- When will the system approach the n -species equilibrium?
- Consistent with our intuition, negative feedbacks maintain diversity when $\alpha < 0$ and positive feedbacks diminish it when $\alpha > 0$



Long-term dynamics: The simplest case

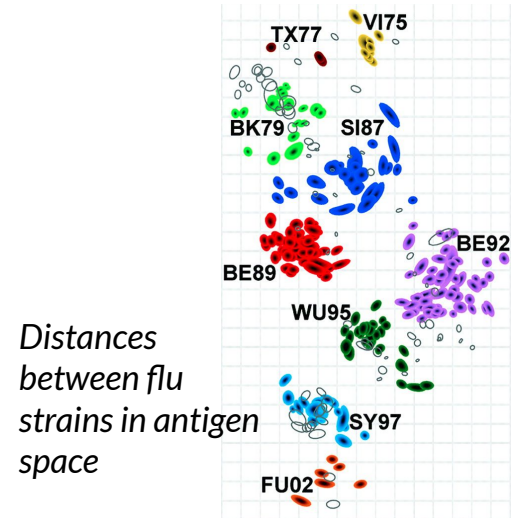
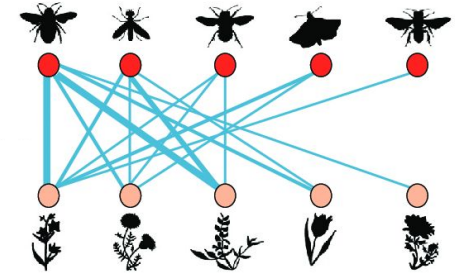
$$P = \alpha I + \beta 11^T$$

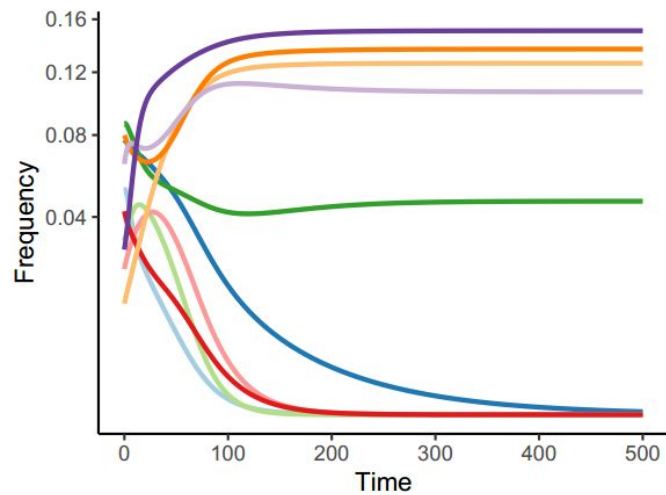
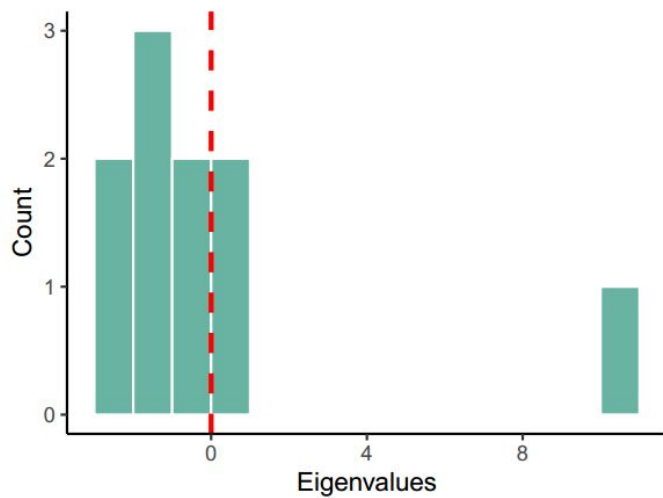
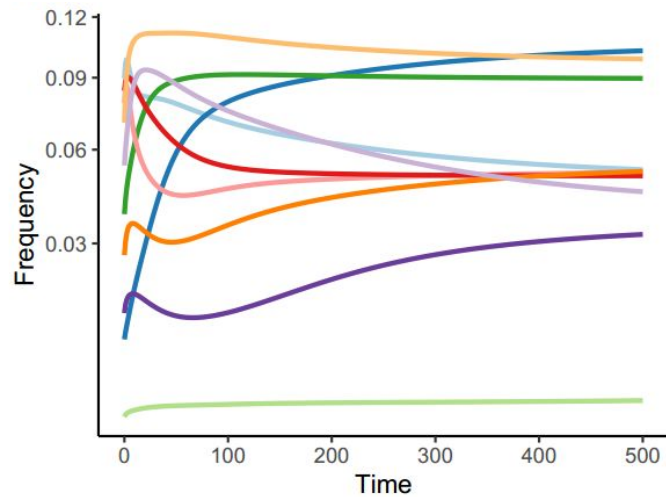
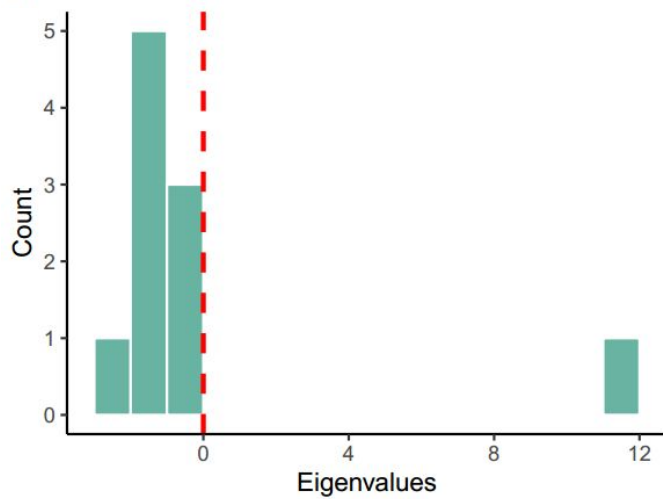
- When will the system approach the n -species equilibrium?
- Consistent with our intuition, negative feedbacks maintain diversity when $\alpha < 0$ and positive feedbacks diminish it when $\alpha > 0$
- Using an embedding technique from dynamical systems theory, we can prove that the coexistence equilibrium is globally stable for $\alpha < 0$
- Demographic differences between species (i.e. $m_i \neq m_j$ and/or $\alpha_i \neq \alpha_j$) never affect stability

Key question: How do we generalize the idea that stable coexistence occurs whenever conspecifics have a disadvantage recolonizing patches?

Arbitrary symmetric P $\leftarrow p_{ij} = p_{ji}$

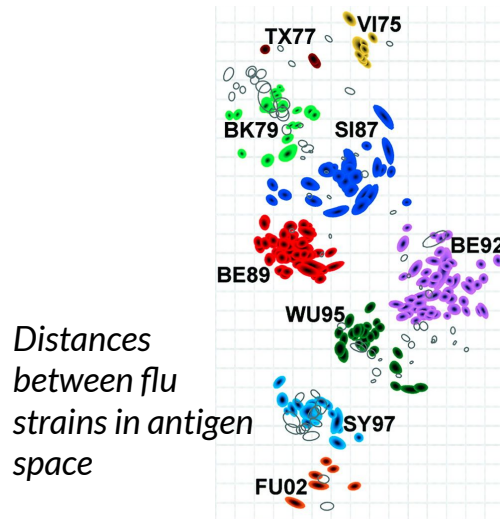
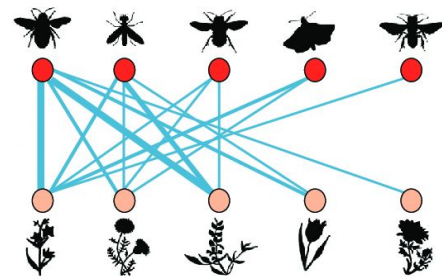
- When $m_i = m$, we can perform local stability analysis for any number of species
- The coexistence equilibrium is stable if and only if P has **exactly 1 positive eigenvalue**





Arbitrary symmetric P

- When $m_i = m$, we can perform local stability analysis for any number of species
- The coexistence equilibrium is stable if and only if P has **exactly 1 positive eigenvalue**
- Numerical evidence indicates that this condition is also sufficient for global stability, unaffected by variation in m_i
- A necessary condition is $p_{ij} > \min(p_{ii}, p_{jj})$
- Eigenvalue condition generalizes the intuitive notion of “**negative feedbacks**” to complex communities



Distances
between flu
strains in antigen
space

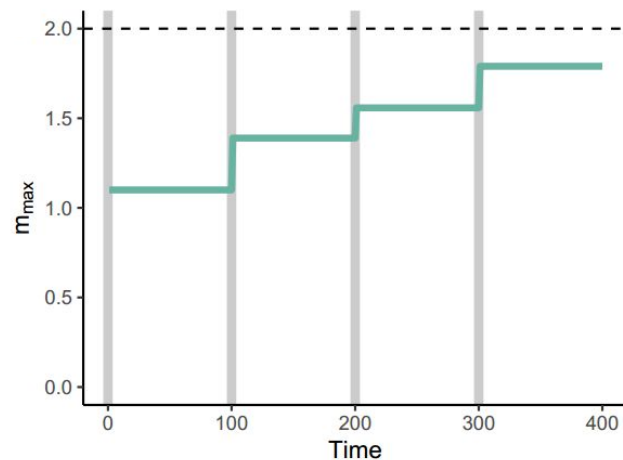
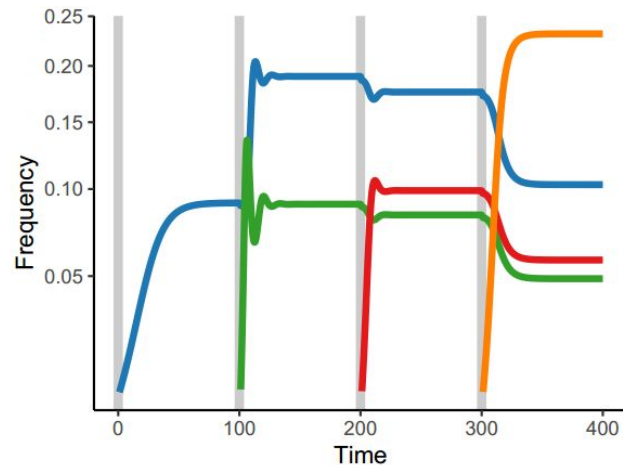
Coexistence induces a positive diversity-robustness relationship

- More diverse communities can tolerate higher local extinction rates
 - e.g. more disturbance, lower environmental quality, etc.

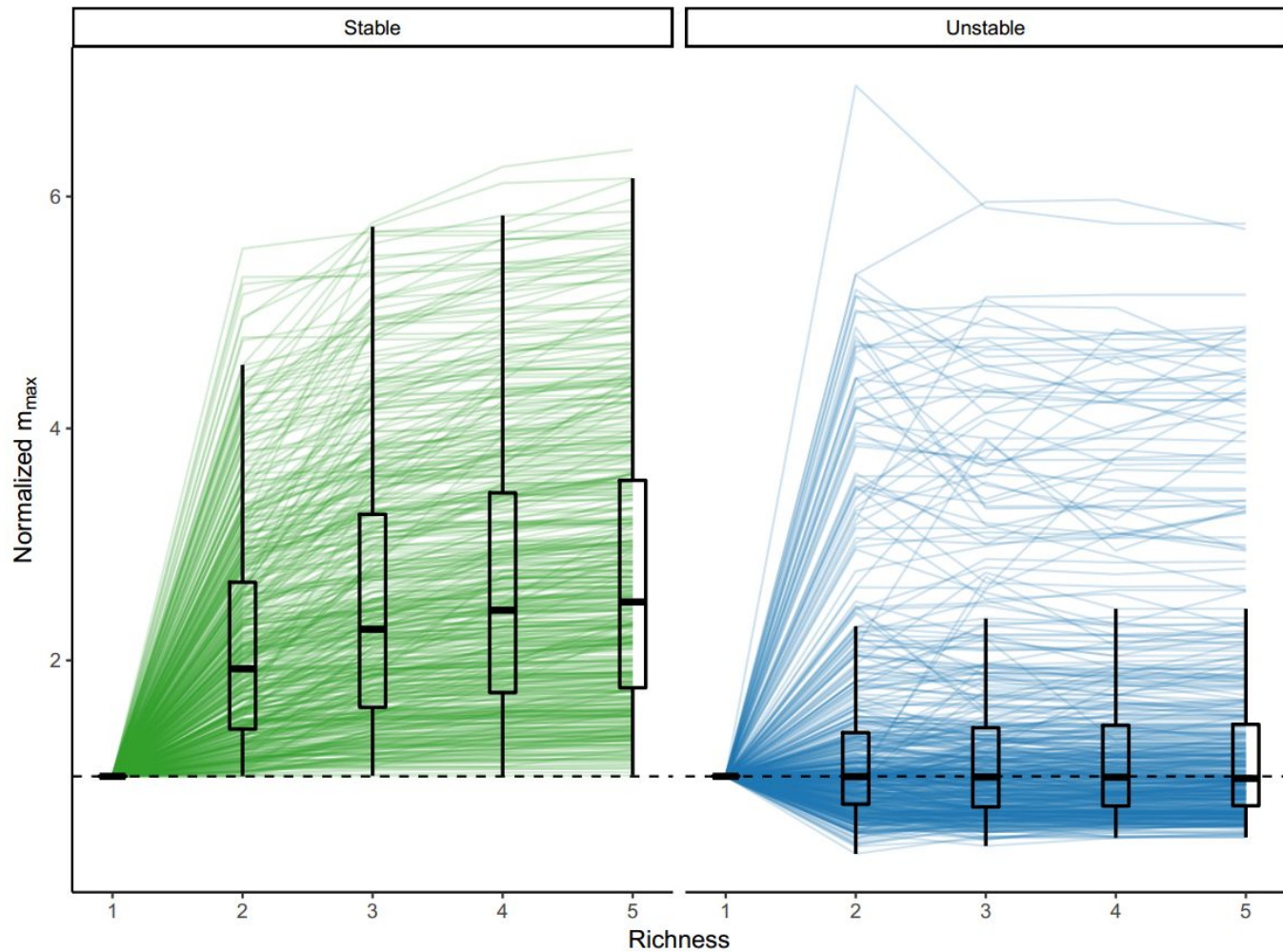
Recalling the simplest model....

$$m < m_{max} = \beta + \frac{\alpha}{n}$$

Maximum sustainable disturbance



Community richness \longrightarrow

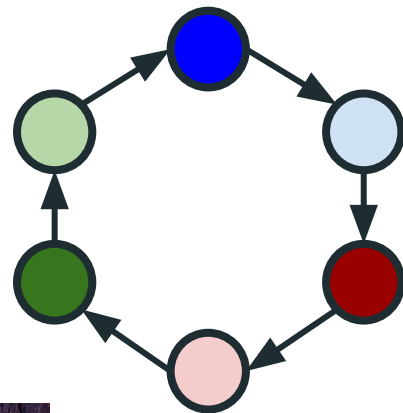


Diversity-robustness relationship in 500 stable and 500 unstable communities

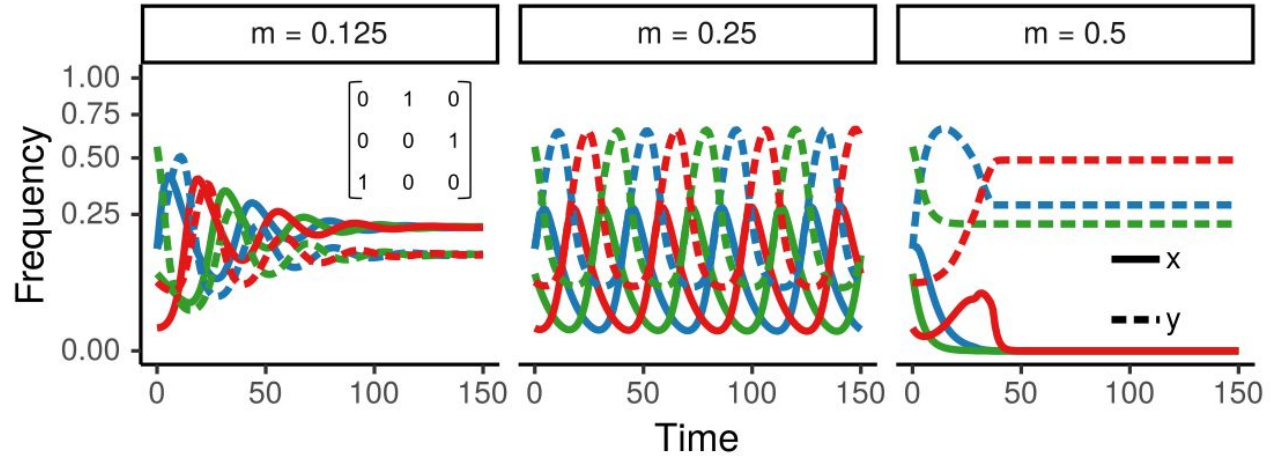
Nonsymmetric P: successional cycles

- An interesting special case is when P is a cyclic permutation matrix (e.g. rock-paper-scissors)
- A “toy” model for successional dynamics

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

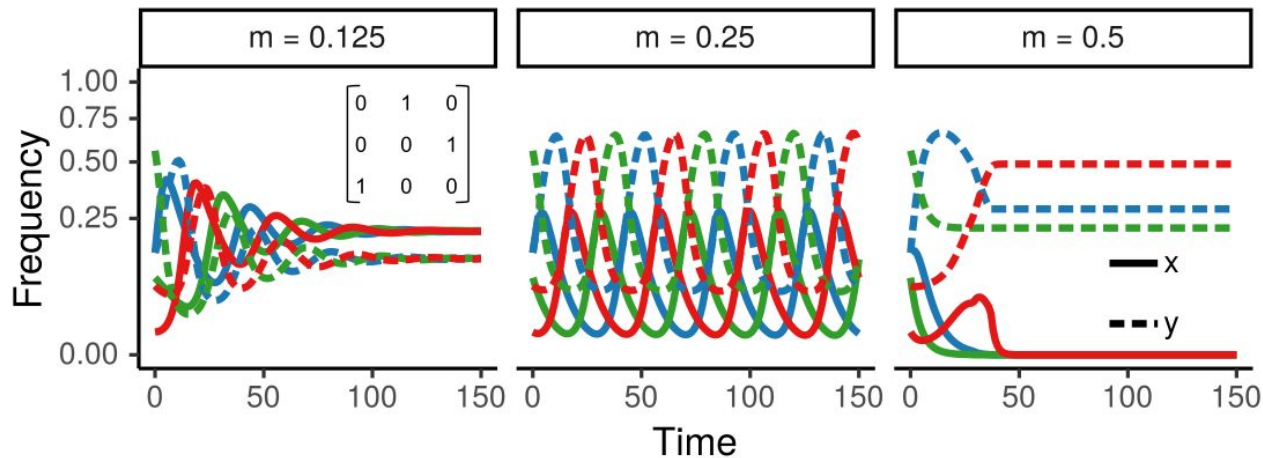


Cyclic P
matrix

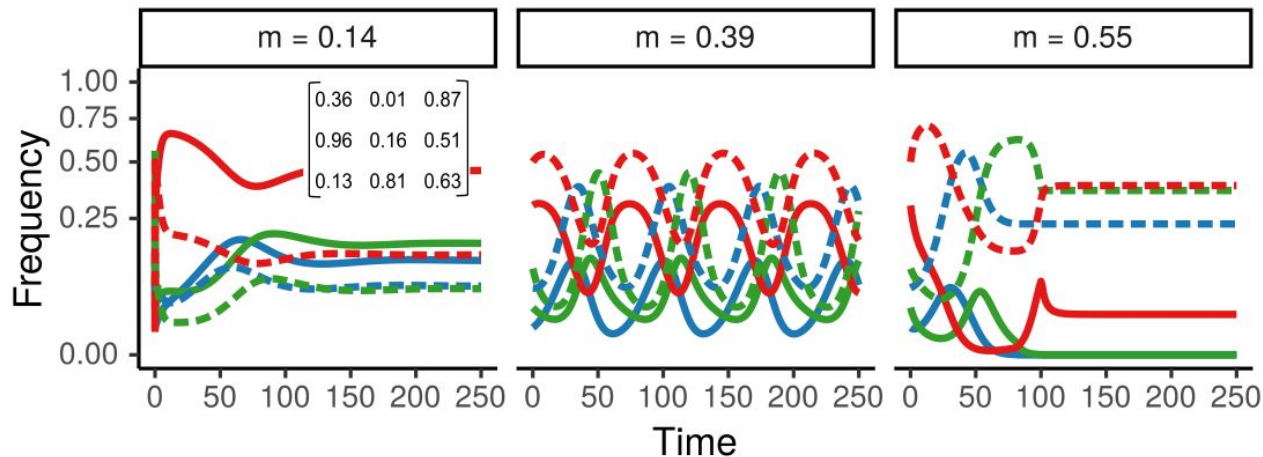


As m grows, the dynamics shift from stable equilibrium (left), to stable limit cycles (center), to instability (right)

Cyclic P
matrix



Random
nonsymmetric
 P matrix



Conclusions

- We introduce a **flexible** and **tractable** model for the dynamics of “ecosystem engineers” interacting in a landscape
- For symmetric P , the condition **P has exactly 1 positive eigenvalue** naturally generalizes the notion of “negative feedbacks for all species”
- Stability condition induces a **positive diversity-robustness relationship**
- For nonsymmetric P , dynamics can be much more **complex**

More details:
Metapopulations
with habitat
modification
(bioRxiv)



Thank you!

And thanks to:

Carlos A. Serván

Paula Lemos-Costa

Abby Skwara

Pablo Lechón

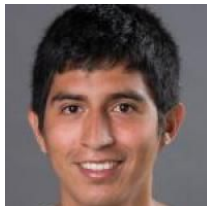
Jacopo Grilli

Theo Gibbs

Dan Maynard

Stefano Allesina (<https://allesinalab.uchicago.edu/>)

for their contributions to this project.



Contact:

zachmiller@uchicago.edu

<https://zacharyrmiller.netlify.app>



This work was supported by
an NSF GRFP (DGE-1746045)